Calibrating a 3D Finite Element Model of TBM Excavation Using Monitoring Data Through Bayesian Approaches

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Tunnel Construction Risks

Key Question: Do tunnel constructions pose risks to people and property on the surface ?

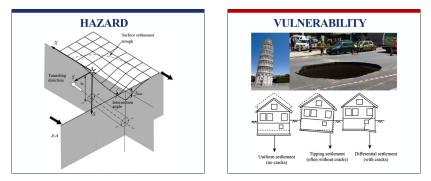


Figure: Surface Settlements (left) and "Fontis" observed during tramway construction in Nice (left)

TBM Earth Pressure Balance (EPB)

Tunnel Boring Machines (TBMs) are commonly used in shallow urban tunnel construction to **minimize soil displacement and mitigate risks effectively**

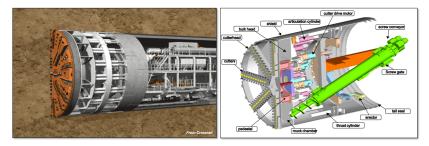


Figure: Tunnel Boring Machine - Earth Pressure Balance Technology

Factors Affecting Soil Displacement

Numerous factors influence soil displacement in shallow urban tunnel construction with TBM $\ensuremath{\mathsf{EPB}}$

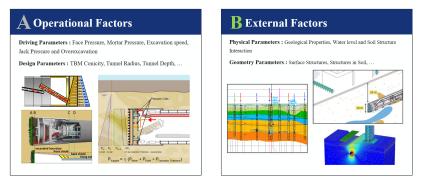


Figure: Factors Affecting Soil Settlements [8] [11]

Physical & Design Parameters

Case study: Segment of Metro Line 16 (approximately 5 km of track)

- □ 24 Geological Cross-Sections examined
- □ 2 Geometrical Parameters per Cross-Section
- □ 4 10 Geological Layers per Cross-Section
- □ 7 11 Mechanical Parameters per Geological Layer

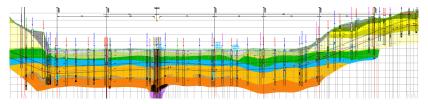


Figure: Metro Line 16 Geology Profile

Operational Factors

 ${\bf 18}\ {\bf sensor}\ {\bf values}\ {\rm have}\ {\rm been}\ {\rm recorded}\ {\rm from}\ {\rm a}\ {\rm sensor}\ {\rm setup}\ {\rm of}\ {\rm 100}\ {\rm parameters}\ {\rm on}\ {\rm th}\ {\rm TBM},\ {\rm with}\ {\rm a}\ {\rm 1}\ {\rm kHz}\ {\rm frequency}$

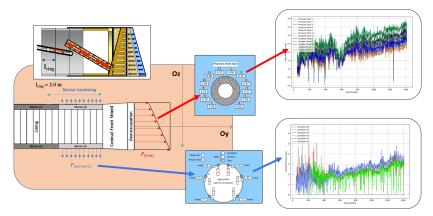


Figure: The Connection Between the Simulator and Measured TBM Driving Parameters

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Surface Monitoring Data

In the study case, $880\ road\ prisms$ are monitored on average every $3\ hours$

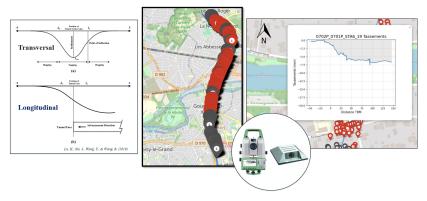


Figure: Illustration of Surface Monitoring Data

New Coordinate System

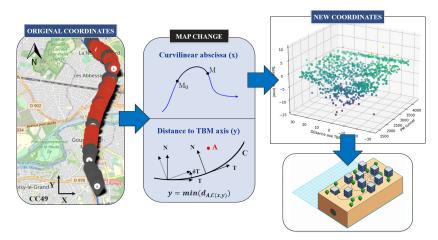


Figure: Process for Changing Map Coordinates

Mapping Settlements

Regressor model

$$z = \zeta(x') + \epsilon_{\zeta} \tag{1}$$

Assumptions made

- \Box ζ as Gaussian Process: $GP(m(\cdot), c(\cdot, \cdot))$ [10]
- \Box Matern Kernel (u = 3/2) for covariance function $c(\cdot, \cdot)$ (anisotropic)
- \Box Constant mean function: $m(\cdot)$
- \Box Gaussian Noise: $\epsilon' \sim N(0, \lambda)$
- \Box Settlements *z* not time-dependent
- \Box x': Position and distance on the tunnel axis (two-column table)
- \Box Hyperparameters include kernel $(\rho_1, \rho_2, \sigma_0)$ and noise (λ)

Settlements Mapping

To conduct this regression, we employ different strategies:

Choose the hyperparameters manually with "expert knowledge"
 RELM algorithm to find the optimal set of hyperparameters

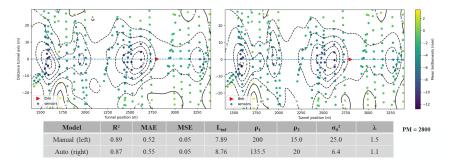


Figure: Regression Results (Python Library: gpmp [12])

How to Estimate Settlements?



Figure: A Variety of Methods for Predicting Settlements [3][13]

To estimate tunnel settlements, a 3D parametric FEM for TBM excavation has been developed in Abaqus [1]



TBM Excavation Modelling

Various strategies can be employed to **model interactions between TBM and soil**

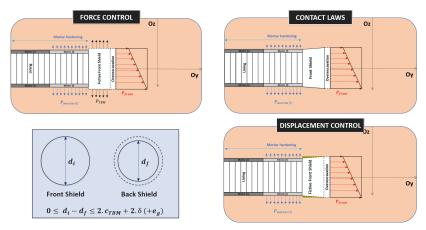


Figure: Different Strategies to model TBM excavation [5]



TBM Excavation Modelling

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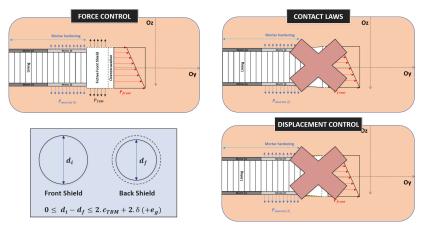


Figure: Different Strategies to model TBM excavation [5]

Geology Properties

Assumptions Regarding Geological Properties:

- Geological materials supposed elastic behaviour with the Mohr-Coulomb yield criterion
- Undrained Conditions (Total Stress) or Drained Conditions (Effective Stress)
- $\hfill\square$ Water flow and water pressure in the soil are not taken into account
- □ K0 process for horizontal stress calcul, assuming horizontal layers

$$\sigma_{\rm eff}^{v}(z) = \int_{0}^{z} \gamma_{\rm soil}(l) dl - \int_{0}^{z} \gamma_{\rm water}(l) dl$$
⁽²⁾

$$\sigma_{\rm tot}^v(z) = \int_0^z \gamma_{\rm soil}(l) dl \tag{3}$$

$$\sigma_{\mathbf{x}}^{h}(z) = K_{0,x}(z).\sigma^{v}(z) \tag{4}$$

$$\sigma_{\mathbf{y}}^{h}(z) = K_{0,y}(z).\sigma^{v}(z)$$
(5)



3D Finite Element Model of TBM Excavation

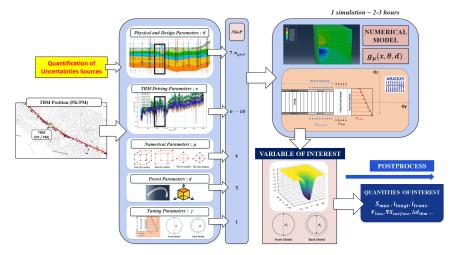


Figure: 3D Parametric Finite Element Model of EPB TBM Excavation[2][6][9]

Calibration Process

The calibration aims to find optimal and acceptable values for θ and γ that best fit the monitoring data

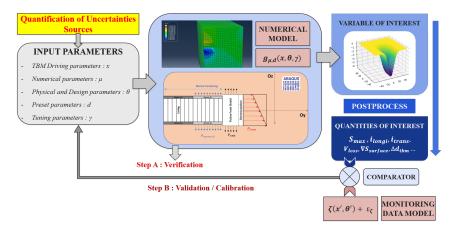


Figure: Objective of TBM Excavation Simulator Calibration [2]

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BlackBox Model

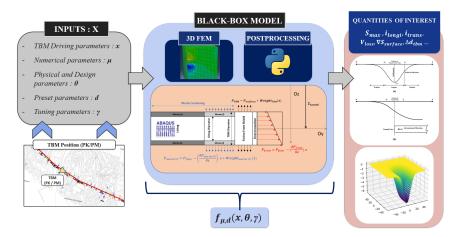


Figure: Modeling the TBM Excavation Simulator using a BlackBox approach

Surrogate Model

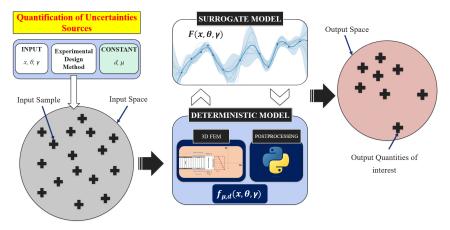


Figure: Surrogate Model of the TBM Excavation Simulator [2]

Before Calibration

Before initiating the calibration process:

- □ Verify simulation convergence for different input points
- Manually validate the model through comparisons with real data or established literature models, [6], following guidelines from organizations like CFMS [4]

The Calibration Problem can be formalized [2][7]

$$z = f_{\mu,d}(x,\theta,\gamma) + \epsilon \tag{6}$$

$$z = f_{\mu,d}(x,\theta,\gamma) + \delta(x) + \epsilon \tag{7}$$



Perspectives and Future Works

- Last Manual Validation of the TBM excavation model
- □ Complete Quantification of Input Uncertainties
- Implement Latin Hypercube Sampling (LHS) and run multiple simulations using high-performance computing
- □ Perform Sensitivity Analysis to reduce Input Dimension
- Develop a Surrogate Model
- □ Test Bayesian Calibration Methods



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