

# Spatial logistic Gaussian process for density field modelling: application to stochastic inverse problems

Athénaïs Gautier   David Ginsbourger   Guillaume Pirot

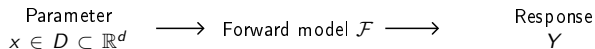
This work has been supported by Swiss National Science Foundation project number 178858

Workshop on Stochastic Simulators  
March 11, 2021

- 1 Motivations: stochastic inverse problems
- 2 Probability density field modelling with the SLGP
- 3 Application to inverse problems: Probabilistic ABC

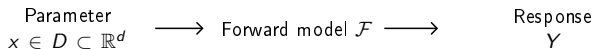
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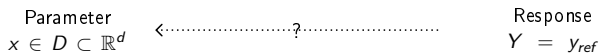


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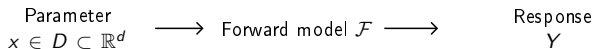


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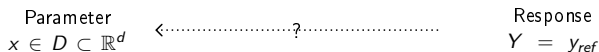


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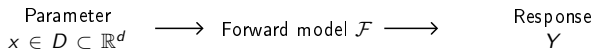


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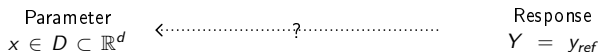
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→ requires the likelihood  $\pi[y_{ref}|x]$  to get the posterior.

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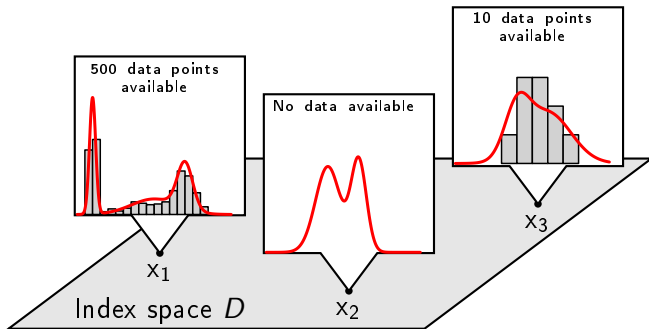
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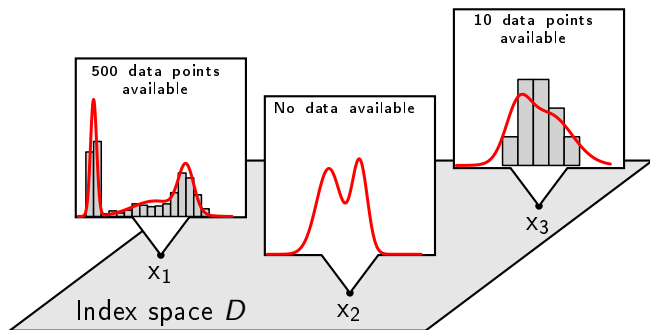
**ABC rejection sampling algorithm:** Uses simulation to approximate the ABC posterior.

- Requires many simulations, many are discarded.
- The sampling of  $x$  must be done with respect to the prior.

# Distribution valued fields and ABC



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Some application fields for ABC

- Epidemiology
- Astrophysics and cosmology
- Geosciences

## One application in hydrogeology 1/2

**Setting:** A contaminant, released at depth  $x$  (0m to 10m.) spreads through an aquifer with unknown geological structure. Given concentration breakthrough curves, we want to find  $x$ .

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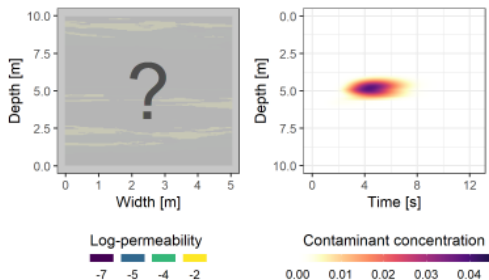


Figure: Reference curves for an unknown geology

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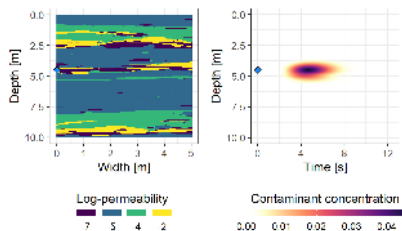
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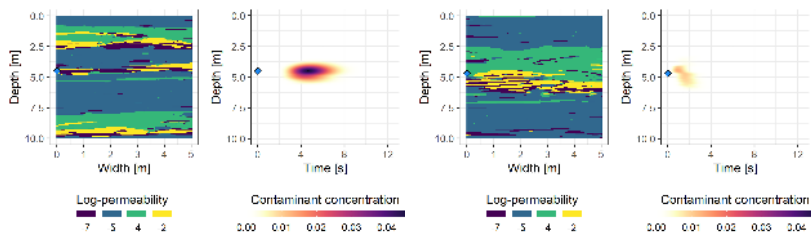


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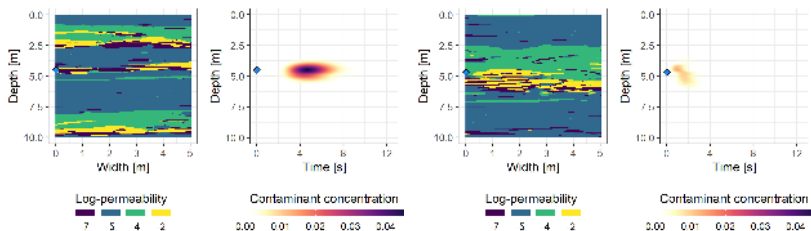
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→ Want to learn the misfit distribution

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## Requirements

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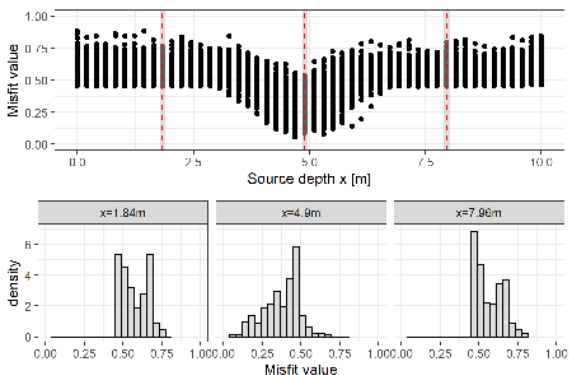
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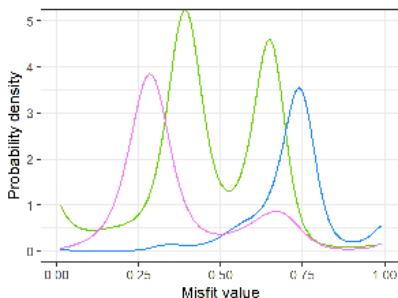
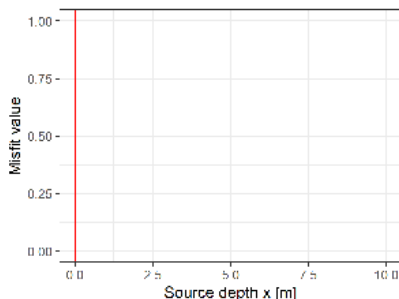
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Under sufficient measurability assumptions on  $W$ , the Spatial Logistic Gaussian Process (SLGP)  $p_x(t)$  is a random pdf field.

# Prior induced by a SLGP<sup>1</sup>

Visualisation of  $p_x(t; \omega_1)$ ,  $p_x(t; \omega_2)$ ,  $p_x(t; \omega_3)$ , with  $x$  varying.



<sup>1</sup>Mean: 0

Kernel: Random Fourier approximation (order 100) of a Matérn 5/2 kernel.  
With variance  $0.01^2$ , lengthscale 0.2 in  $t$  (range  $[0, 1]$ ) and 2 in  $x$  (range  $[0, 10]$ )

## Some references

- Tom Leonard (1978). “Density Estimation, Stochastic Processes and Prior Information”. In: *Journal of the Royal Statistical Society. Series B (Methodological)*. URL: <http://www.jstor.org/stable/2984749>
- Surya Tokdar and Jayanta K. Ghosh (2007). “Posterior consistency of logistic Gaussian process priors in density estimation”. In: *Journal of Statistical Planning and Inference*. DOI: 10.1016/j.jspi.2005.09.005
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## Challenge for implementation

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$$\forall x \in D, t \in \mathcal{T}, W_{x,t} = \sum_{j=1}^p \sqrt{\lambda_j} f_j(x, t) \varepsilon_j$$

$p \in \mathbb{N}$ ,  $\lambda_j > 0$ ,  $f_j$ 's are functions on  $D \times \mathcal{T}$  and  $\varepsilon_j$ 's are i.i.d.  $\mathcal{N}(0, 1)$ .

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→ Can approximate the integral with a quadrature scheme

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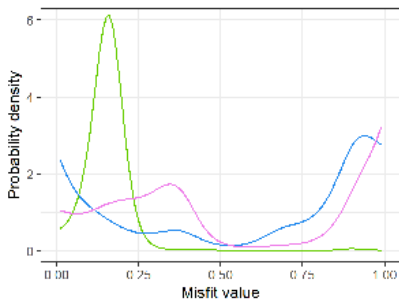
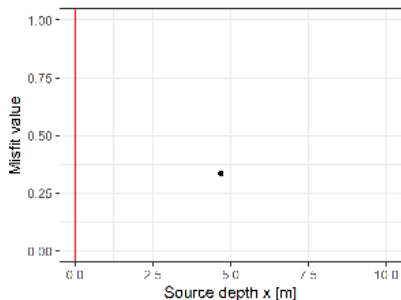
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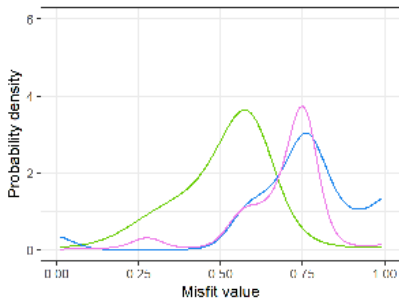
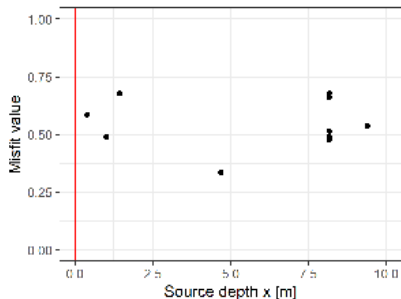
→ Could be implemented within a MCMC framework.

SLGP<sup>1</sup> conditioned on observations,  $n=1$ 


---

<sup>1</sup>Mean: 0

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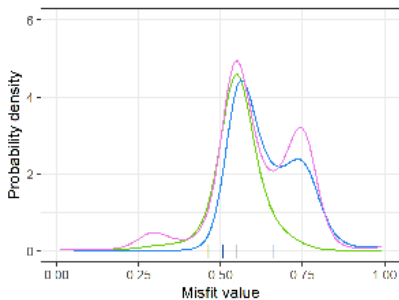
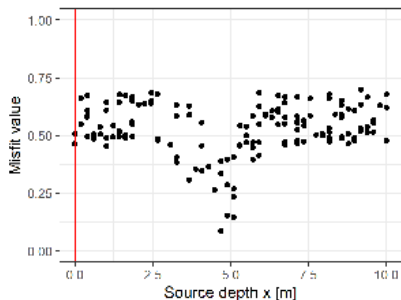
SLGP<sup>1</sup> conditioned on observations,  $n=10$ 


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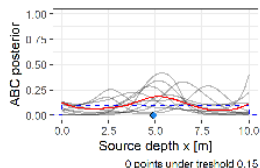
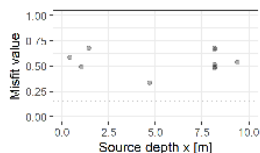
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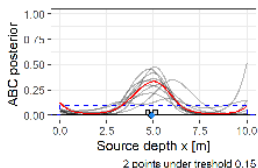
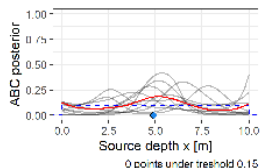
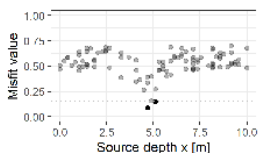
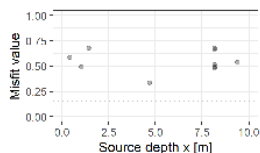


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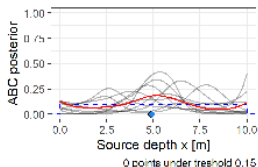
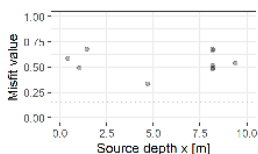
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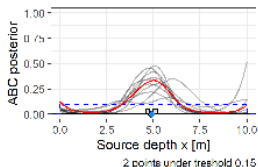
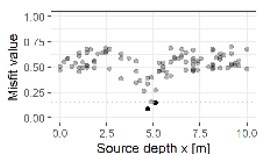
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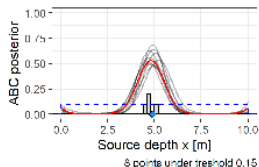
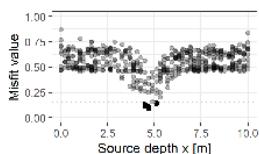
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## Conclusion and upcoming work

In this work we:

- Presented a Bayesian non parametric density field model
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**Thank you for your attention!**

# Random Fourier Features

Assume  $k$  is stationary, we approximate  $k$  with  $k_{RFF}$  defined as:

$$k_{RFF}(x, y) := \frac{\sigma^2}{2\pi p} \sum_{i=1}^p \cos(\omega_i^T x + u_i) \cos(\omega_i^T y + u_i) \quad (4)$$

where  $\sigma^2 = k(0, 0)$ , the  $\omega_i$ 's are draws of independent random variables that have a density equal to spectral density associated to  $k$  and the  $u_i$ 's are draws of i.i.d.  $\mathcal{U}(0, 2\pi)$ .

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It satisfies  $\mathbb{E}[k_{RFF}] = k$

$W_{RFF}(x) := \frac{\sigma}{\sqrt{2\pi p}} \sum_{i=1}^p \epsilon_i \cos(\omega_i^T x + u_i)$  where  $\epsilon_i$  are i.i.d.  $\mathcal{N}(0, 1)$ ,  
is a  $\text{GP}(0, k_{RFF}(x, y))$ .

# Estimating the hyperparameters of the GP

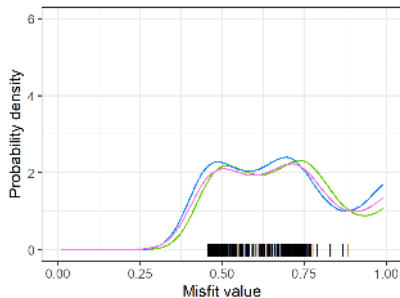
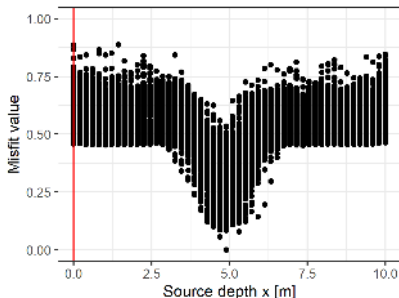
Assume  $k$  depends on two types of parameters, a variance parameter  $\sigma^2 > 0$  and a some strictly positive length-scale  $\theta$ :

$$\forall x, y \in (D \times \mathcal{T})^2, k(x, y) = \sigma^2 k_0(D_{1/\theta}(x - y)) \quad (5)$$

where  $D_{1/\theta}$  is the diagonal matrix with diagonal  $1/\theta$ .

Setting a prior distribution  $\Lambda$  over  $(\sigma^2, \theta)$  enables us to do a Bayesian estimation of the parameters.

# SLGP<sup>1</sup> conditioned on the full data set, $n=10000$



<sup>1</sup>Mean: 0

Kernel: Random Fourier approximation (order 100) of a Matérn 5/2 kernel.  
With variance and lengthscale sampled

## Fit on the full data set: parameters estimated

